Network Formation II - Strategic Networks

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Game Theoretic Models of Network Formation

In the game theoretic models of network formation, we should consider:

- Costs and benefits for each agent associated with each network
- Agents may choose links
- Contrast incentives and social efficiency

Some important questions:

- Which networks are likely to form?
- Are the networks that form stable or efficient?
- Can interventions improve efficiency?
- Can such models provide insight into observed characteristics of networks?

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Modelling Choices

How should we model incentives for form and sever links?

- Is consensus needed? (directed or undirected links)
- Can agents coordinate changes in the network?
- Is the process dynamic or static?
- What do agents know when making a decision?
- Can they compensate each other for the friendship?
- How sophisticated are agents? Do they make errors?
- What happens on the network?

An Economic Analysis - Jackson Wolinsky (1996)

An Undirected Network Formation model:

- $u_i(g)$: payoff to i if the network is g
- $0 \le \delta \le 1$: benefit parameter for i from connection between i and j
- $c_{ij} \ge 0$: cost to i of link to j
- $\bullet \ l(i,j):$ shortest path length between $i, \ j$

Therefore the payoff function is:

$$u_i(g) = \sum_{j}^{N} \left(\delta^{l(i,j)} - g_{ij} c_{ij} \right)$$

$$= \sum_{j}^{N} \delta^{l(i,j)} - \sum_{j \in N_i(g)} c_{ij}$$
(1)

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- $\bullet\,$ Benefit from a friend is $\delta<1$
- Benefit from a friend of a friend is δ^2
- cost of a link is c > 0



u₂= δ+ δ² -c







 $u_3 = \delta + \delta^2 + \delta^3 + \delta^4 - c$



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Modelling Incentives and Equilibirum

Some Questions:

- Which networks are best for society?
- Which networks are formed by agents?

How to Model:

- Model this as a game where each agent announce who they wish to be linked to simultaneously.
- Links are formed if and only if both agents name each other.
- Since both agents need to confirm to form a link, the equilibrium concept is Nash equilibrium.
- In equilibrium, no agent can benefit from changing his actions, i.e. forming new links or severing other links.

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Equilibrium Example With Two Agents



Both announce each other is an equilibrium (yes,yes). Neither announces the other is an equilibrium (no, no)

Pairwise Stability

We have pairwise stability when:

• No agent benefits from severing a link: relationships must be beneficial to be maintained.

$$u_i(g) \ge u_i(g-ij) \quad \forall i, ij \in g$$

• No two agents both benefit from adding a link (at least one strictly): beneficial relationships are pursued when available.

 $u_i(g+ij) \ge u_i(g)$ implies $u_j(g+ij) < u_j(g)$ for $ij \notin g$

• A weak concept, but often narrows things down.

Pairwise Stability





Efficiency

- Pareto Efficient Network g: There does not exist g' such that $u_i(g') \ge u_i(g)$ for all i with strict inequality for some.
- Efficient Network g (or strong efficiency): A network g is called efficient if $\sum_i u_i(g) \ge \sum_i u_i(g')$ for all $g' \in G$.
- There always exist at least one efficient network, given that there are only finitely many networks.

Efficiency



Externalities

• Positive Externality:

$$u_k(g+ij) \ge u_k(g)$$
 if $ij \notin g$, $\forall k \neq i, j$

• Negative Externality:

$$u_k(g+ij) \le u_k(g)$$
 if $ij \notin g$, $\forall k \ne i, j$

• There are inefficiencies due to positive or negative externalities.

Back to Jackson Wolinsky (1996)

An Undirected Network Formation model:

- $\bullet \ u_i(g)$: payoff to i if the network is g
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- $c_{ij} \ge 0$: cost to *i* of link to *j*
- l(i,j): shortest path length between i, j

Therefore the payoff function is:

$$u_i(g) = \sum_{j}^{N} \left(\delta^{l(i,j)} - g_{ij} c_{ij} \right)$$
$$= \sum_{j}^{N} \delta^{l(i,j)} - \sum_{j \in N_i(g)} c_{ij}$$

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Bloch-Jackson 2005 Model

Distance Based Utility Model:

• Payoff to *i* if the network is *g*:

$$u_i(g) = \sum_j^N \left(bl(i,j) \right) - d_i(g)c \right)$$

- $\bullet \ b(l):$ decreasing benefit function for i from connection between i and j
- $c \ge 0$: cost to i of link to j
- $\bullet \ l(i,j):$ shortest path length between $i,\ j$

- Benefit from a friend is b(1)
- Benefit from a friend of a friend is b(2) < b(1)
- cost of a link is c > 0

 $u_2 = 3b(1) + b(2) - 3c$



The unique efficient network structure in the distance-based model is:

- Complete network is b(2) < b(1) c
- Star encompassing all nodes if $b(1) b(2) < c < b(1) + \frac{(n-2)}{2}b(2)$
- Empty network if $b(1) + \frac{(n-2)}{2}b(2) < c$

Inefficiencies in Connection Model is due to positive externalities.

In the distance-based connection model is:

- At low cost c < b(1) b(2): Complete network is pairwise stable.
- At medium low cost b(1) b(2) < c < b(1): Star network is pairwise stable, but there are other pairwise stable networks as well.
- At medium high cost $b(1) < c < b(1) + \frac{(n-2)}{2}b(2)$: Star network is not pairwise stable.
- At high cost $b(1) + \frac{(n-2)}{2}b(2) < c$: Empty network is the only pairwise stable network.

Externality

Look at the following example to see why for example at medium high cost star is not pairwise stable:

- Payoff to the center agent: 3b(1) 3c.
- Not pairwise stable if b(1) < c.
- But overall payoff is 6b(1) + 6b(2) 6c.
- Central agent does not account for the fact that peripheral players gain indirect benefits.



Tension Between Stability & Efficiency



Summary

Strength of economics approach:

- Payoffs allow for welfare analysis (incentives vs efficiency)
- Tie the nature of externalities to network formation

Challenges to economic approach:

- Overly regular network structures emerge from models: Need for some heterogeneity
- How to identify payoff structure in applications?