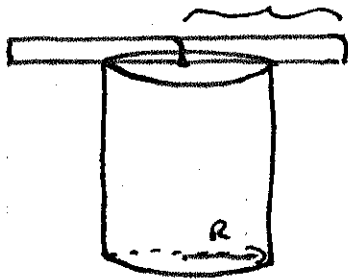
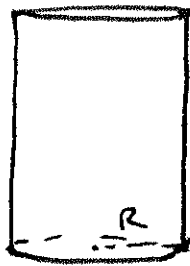


Ch. 13
#82. Before



After



$l = 0.78 \text{ m}$
 $M_{\text{arm}} = 2.5 \text{ kg}$
 $M_{\text{cylinder}} = 40 \text{ kg}$
 $R = 0.2 \text{ m}$

$$I_{\text{before}} = I_{\text{cylinder}} + 2I_{\text{rod}}$$

$$I_{\text{cylinder}} = \frac{1}{2} M_{\text{cylinder}} R^2$$

$$I_{\text{rod}} = \frac{1}{3} M_{\text{arm}} l^2$$

$$\Rightarrow I_{\text{before}} = \frac{1}{2} M_{\text{cylinder}} R^2 + \frac{2}{3} M_{\text{arm}} l^2$$

$$I_{\text{after}} = I_{\text{cylinder}}$$

$$= \frac{1}{2} M_{\text{TOT}} R^2$$

$$I_{\text{after}} = \frac{1}{2} M_{\text{TOT}} R^2$$

Since no external torques are acting, angular momentum is conserved.

$$\vec{L}_{\text{before}} = \vec{L}_{\text{after}}$$

$$\Rightarrow |\vec{L}_{\text{before}}| = |\vec{L}_{\text{after}}|$$

$$\Rightarrow I_{\text{before}} |\vec{\omega}_{\text{before}}| = I_{\text{after}} |\vec{\omega}_{\text{after}}|$$

$$\Rightarrow |\vec{\omega}_{\text{after}}| = \frac{I_{\text{before}}}{I_{\text{after}}} |\vec{\omega}_{\text{before}}|$$

$$|\vec{\omega}_{\text{after}}| = \frac{\frac{1}{2} M_{\text{cylinder}} R^2 + \frac{2}{3} M_{\text{arm}} l^2}{\frac{1}{2} M_{\text{TOT}} R^2} |\vec{\omega}_{\text{before}}|$$

Since $M_{\text{TOT}} = M_{\text{cylinder}} + 2M_{\text{arm}}$, $M_{\text{cylinder}} = M_{\text{TOT}} - 2M_{\text{arm}}$

$$|\vec{\omega}_{\text{after}}| = \frac{\frac{1}{2} M_{\text{TOT}} R^2 + 2M_{\text{arm}} \left(\frac{1}{3} l^2 - \frac{1}{2} R^2 \right)}{\frac{1}{2} M_{\text{TOT}} R^2} |\vec{\omega}_{\text{before}}|$$

$$= \left(1 + \frac{4M_{\text{arm}}}{M_{\text{TOT}}} \left(\frac{\frac{1}{3} l^2 - \frac{1}{2} R^2}{R^2} \right) \right) |\vec{\omega}_{\text{before}}|$$

$$|\vec{\omega}_{\text{after}}| = \left(1 + \frac{4 M_{\text{arm}}}{6 M_{\text{TOT}}} \left(\frac{2l^2 - 3R^2}{R^2} \right) \right) |\vec{\omega}_{\text{before}}|$$

$$|\vec{\omega}_{\text{after}}| = \left\{ 1 + \frac{2}{3} \frac{M_{\text{arm}}}{M_{\text{TOT}}} \left(2 \left(\frac{l}{R} \right)^2 - 3 \right) \right\} |\vec{\omega}_{\text{before}}|$$

for $M_{\text{arm}} = 2.5 \text{ kg}$
 $M_{\text{TOT}} = 45 \text{ kg}$

$$l = 0.78 \text{ m}$$

$$R = 0.2 \text{ m}$$

$$|\vec{\omega}_{\text{after}}| = \left\{ 1 + \frac{2}{3} \frac{2.5 \text{ kg}}{45 \text{ kg}} \left(2 \left(\frac{0.78}{0.2} \right)^2 - 3 \right) \right\} |\vec{\omega}_{\text{before}}|$$

$$= \left\{ 1 + \frac{2}{3} \frac{1}{18} \left(2 \cdot (3.9)^2 - 3 \right) \right\} |\vec{\omega}_{\text{before}}|$$

$$= \left\{ 1 + \frac{1}{27} \left(2 \cdot (15.21) - 3 \right) \right\} |\vec{\omega}_{\text{before}}|$$

$$= \left\{ 1 + \frac{1}{27} \left(30.42 - 3 \right) \right\} |\vec{\omega}_{\text{before}}|$$

$$= \left\{ 1 + \frac{27.42}{27} \right\} |\vec{\omega}_{\text{before}}|$$

$$|\vec{\omega}_{\text{after}}| = 2.02 |\vec{\omega}_{\text{before}}|$$

for $|\vec{\omega}_{\text{before}}| = 1.5 \text{ rpm}$ ← note, this is ridiculously slow
 they probably meant rev per sec.

$$|\vec{\omega}_{\text{after}}| = 2.02 \cdot 1.5 \text{ rpm} = 3.02 \text{ rpm}$$

$$|\vec{\omega}_{\text{after}}| = 3.02 \text{ rpm} = 0.0504 \frac{\text{rev}}{\text{sec}}$$