# 18 Isometries

# **Basic Properties**

Recall that the distance between two points  $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$  is given by

$$dist(\mathbf{x}, \mathbf{y}) = ||\mathbf{x} - \mathbf{y}|| = \sqrt{(\mathbf{x} - \mathbf{y}) \cdot (\mathbf{x} - \mathbf{y})}.$$

**Definition.** A function  $F \in \operatorname{Trans}(\mathbb{R}^n)$  is an *isometry* if every  $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$  satisfy

$$\operatorname{dist}(F(\mathbf{x}), F(\mathbf{y})) = \operatorname{dist}(\mathbf{x}, \mathbf{y})$$

In words, we say that a function F is an isometry if it preserves distances. Isometries are also called *rigid* transformations and we view them as the natural family of transformations that preserve the "structure" of Euclidean space.

**Example:** In  $\mathbb{R}^2$  (as we will prove) every rotation  $R_{\mathbf{x},\theta}$  and every mirror  $M_L$  is an isometry.

Our goal is to develop an understanding of isometries. The next two lemmas take a couple of steps toward this goal.

Lemma 18.1. Every translation is an isometry

*Proof.* For the translation  $T_{\mathbf{z}}$  and  $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$ . We have

$$\operatorname{dist}(T_{\mathbf{z}}(\mathbf{x}), T_{\mathbf{z}}(\mathbf{y})) = \operatorname{dist}(\mathbf{z} + \mathbf{x}, \mathbf{z} + \mathbf{y}) = ||(\mathbf{z} + \mathbf{x}) - (\mathbf{z} + \mathbf{y})|| = ||\mathbf{x} - \mathbf{y}|| = \operatorname{dist}(\mathbf{x}, \mathbf{y}) \quad \Box$$

**Lemma 18.2.** The set of all isometries of  $\mathbb{R}^n$  is a subgroup of  $\operatorname{Trans}(\mathbb{R}^n)$ 

*Proof.* We need to show identity containment and closure under multiplication and inverses. (*identity*) It is immediate from the definition that the identity is an isometry. (*mult. closure*) If F, G are isometries of  $\mathbb{R}^n$  and  $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$  then

$$\operatorname{dist}(FG(\mathbf{x}), FG(\mathbf{y})) = \operatorname{dist}(F(G(\mathbf{x})), F(G(\mathbf{y}))) = \operatorname{dist}(G(\mathbf{x})), G(\mathbf{y})) = \operatorname{dist}(\mathbf{x}, \mathbf{y}).$$

It follows that FG is an isometry, thus establishing closure under multiplication. (*inverses*) Let F be an isometry and let  $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$ . Since F is an isometry

$$\operatorname{dist}(F^{-1}(\mathbf{x}), F^{-1}(\mathbf{y})) = \operatorname{dist}(F(F^{-1}(\mathbf{x})), F(F^{-1}(\mathbf{y}))) = \operatorname{dist}(\mathbf{x}, \mathbf{y})$$

and it follows that  $F^{-1}$  is also an isometry. This establishes closure under inverses.

*Proof.* To prove this lemma, it suffices to show that whenever  $\mathbf{x}, \mathbf{y}, \mathbf{z}$  lie on a line, then  $F(\mathbf{x}), F(\mathbf{y}), F(\mathbf{z})$  lie on a line. So assume  $\mathbf{x}, \mathbf{y}, \mathbf{z}$  lie on a line with  $\mathbf{y}$  between  $\mathbf{x}$  and  $\mathbf{z}$ . Then

$$dist(\mathbf{x}, \mathbf{z}) = dist(\mathbf{x}, \mathbf{y}) + dist(\mathbf{y}, \mathbf{z})$$
  

$$\Rightarrow dist(F(\mathbf{x}), F(\mathbf{z})) = dist(F(\mathbf{x}), F(\mathbf{y})) + dist(F(\mathbf{y}), F(\mathbf{z}))$$
  

$$\Rightarrow F(\mathbf{x}), F(\mathbf{y}), F(\mathbf{z}) \text{ lie on a line with } \mathbf{y} \text{ between } \mathbf{x} \text{ and } \mathbf{z}$$

giving the desired conclusion.

### Symmetry

**Definition.** A symmetry of a set  $S \subseteq \mathbb{R}^n$  is an isometry  $F \in \text{Trans}(\mathbb{R}^n)$  so that F(S) = S.

**Proposition 18.4.** For every  $S \subseteq \mathbb{R}^n$ , the set of symmetries of S is a subgroup of Trans(S).

*Proof.* Let  $\mathcal{G}$  be the set of symmetries of S. We need to prove that  $\mathcal{G}$  contains the identity, is closed under products, and closed under inverses.

(*identity*) The identity I satisfies I(S) = S so  $I \in \mathcal{G}$ .

(mult. closure) If  $F, G \in \mathcal{G}$  then F(S) = S and G(S) = S we find that FG(S) = F(G(S)) = F(S) = S and thus  $FG \in \mathcal{G}$ .

(inverses) Finally, if  $F \in \mathcal{G}$  then F(S) = S so F maps S bijectively to S. It follows that  $F^{-1}$  also maps S bijectively to S, so  $F^{-1} \in \mathcal{G}$ .

# Linearity

**Definition.** A function  $F : \mathbb{R}^n \to \mathbb{R}^m$  is called *linear* if it satisfies the following properties:

- (1) For every  $\mathbf{x} \in \mathbb{R}^n$  and every  $t \in \mathbb{R}$  we have  $F(t\mathbf{x}) = tF(\mathbf{x})$ .
- (2) For every  $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$  we have  $F(\mathbf{x} + \mathbf{y}) = F(\mathbf{x}) + F(\mathbf{y})$ .

Note: If F is linear, then there exists an  $m \times n$  matrix A so that the function F is given by the rule  $F(\mathbf{x}) = A\mathbf{x}$ .

**Definition.** We say that a function F fixes  $\mathbf{x}$  if  $F(\mathbf{x}) = \mathbf{x}$ .

#### Lemma 18.5. Every isometry that fixes 0 is linear.

*Proof.* Let  $F \in \text{Trans}(\mathbb{R}^n)$  be an isometry that satisfies  $F(\mathbf{0}) = \mathbf{0}$ . We will show that F satisfies (1) and (2) in the definition of linear.

To prove (1) let  $\mathbf{x} \in \mathbb{R}^n$  and let  $t \in \mathbb{R}$ . If  $\mathbf{x} = \mathbf{0}$  then  $F(t\mathbf{x}) = F(\mathbf{0}) = \mathbf{0} = t\mathbf{0}$ . So, we may assume  $\mathbf{x} \neq \mathbf{0}$ . Let  $\mathbf{y} = F(\mathbf{x})$  and observe that since F is an isometry fixing  $\mathbf{0}$  we must have

$$||\mathbf{x}|| = \operatorname{dist}(\mathbf{x}, \mathbf{0}) = \operatorname{dist}(\mathbf{y}, \mathbf{0}) = ||\mathbf{y}||$$

Define  $L_{\mathbf{x}}$  to be the line  $\text{Span}(\mathbf{x})$  and  $L_{\mathbf{y}}$  to be the line  $\text{Span}(\mathbf{y})$  and note that Lemma 18.3 shows that  $F(L_{\mathbf{x}}) = L_{\mathbf{y}}$ . Now,  $t\mathbf{x}$  is the unique point on  $L_{\mathbf{x}}$  that has distance  $||t\mathbf{x}||$  to  $\mathbf{0}$  and distance  $||(t-1)\mathbf{x}||$  to  $\mathbf{x}$ . Similarly,  $t\mathbf{y}$  is the unique point on  $L_{\mathbf{y}}$  that has distance  $||t\mathbf{y}||$  to  $\mathbf{0}$  and distance  $||(t-1)\mathbf{y}||$  to  $\mathbf{y}$ . It follows that  $F(t\mathbf{x}) = t\mathbf{y} = tF(\mathbf{x})$  as desired.

To prove (2) let  $\mathbf{x}, \mathbf{x}' \in \mathbb{R}^n$ . Since F is an isometry, it must map the midpoint between  $\mathbf{x}$  and  $\mathbf{x}'$  to the midpoint between their images  $F(\mathbf{x})$  and  $F(\mathbf{x}')$ , so

$$F(\frac{1}{2}\mathbf{x} + \frac{1}{2}\mathbf{x}') = \frac{1}{2}F(\mathbf{x}) + \frac{1}{2}F(\mathbf{x}').$$

It follows from (1) that

$$\frac{1}{2}F(\mathbf{x} + \mathbf{x}') = F(\frac{1}{2}\mathbf{x} + \frac{1}{2}\mathbf{x}').$$

Combining these equations gives  $F(\mathbf{x} + \mathbf{x}') = F(\mathbf{x}) + F(\mathbf{x}')$  as desired.

Lemma 18.6. Every isometry is an affine transformation.

*Proof.* Let  $F \in \text{Trans}(\mathbb{R}^n)$  be an isometry and let  $\mathbf{y} = F(\mathbf{0})$ . Now we may define the transformation  $G = T_{-\mathbf{y}}F$  and we have

$$G(\mathbf{0}) = T_{-\mathbf{y}}F(\mathbf{0}) = T_{-\mathbf{y}}(\mathbf{y}) = \mathbf{0}$$

It follows from Lemma 18.5 that G is linear, so we may choose a matrix A so that  $G(\mathbf{x}) = A\mathbf{x}$ . Now  $F = (T_{-\mathbf{y}})^{-1}G = T_{\mathbf{y}}G$  so F is given by the rule  $F(\mathbf{x}) = A\mathbf{x} + \mathbf{y}$ , so F is an affine transformation.